CIS 525 Software Development of Parallel and Distributed systems

# **RAPID PROTOTYPING**

- Rapid Prototyping tool
- Behavioral validation
- Environmental integration

## 1. What it does?

- To express specification
- To satisfy corresponding properties
- To generate programs adapted to target architectures

# 2. Issues of automatization of Rapid Prototyping:

- How to get parallel activities from specification?
- How to allow interfaces between the created prototype and its environment?
- How to optimize generated code?

# **3.** Formal approach allows major advances in:

- Reliability
- Robustness
- Modification
- Reusability

# 4. Verification of systems before installation:

- Large cost reduction in development and maintenance
- Petri nets allow validation of behavioral properties (locks, etc.)

• Petri nets allow abstractions of subsets of the outside environment the prototype has to deal with

## Main ideas:

- management of external environment interfaces
- description of the complete process

# Specification:

- modeling of the system behavior
- modeling of the prototype environment behavior (needed to validate the system behavior in its environment) calls of interface primitives are required

**EXAMPLE:** Data processing of characters between 3 processes

- Petri net model has to be compilable (i.e. it is well structured and respects some properties)
- Compilable model may be decomposed into sets of objects
- The decomposition is performed before code generation

# Types of software objects involved

**1. Process** – subsets satisfying invariant properties and characterize a possible concurrent program unit

**2.** state\_process – is a place belonging to a process (simple, alternative, terminate)

- **3. Resource** private, shared
- **4.** Action (from transitions) can be:

- simple (one process)
- synchronized (>=2)
- guarded (resources)

**Definition:** A prototyping process is a mapping from a Petri net to a prototype.

# **Steps of Prototyping Process**

- **1. Identification:** (neither language nor architecture dependent)
- Identifies and checks the use of external components
- Behavioral validation of external component must happen before validation
- **2.** Analysis: (neither language nor architecture dependent)
- Decomposing the model into sets of objects (using Petri net invariants called also semi-flows)
- Several decompositions are possible and all of them can be explored
- **3. Location Step:** (architecture dependent)
- Distributes instances of the process decomposition upon the target architecture (if several processors) external component location constraints have to be taken into account
- 4. Code Generation: (target language dependent)
- Prototype manages control of all actions described under specification

- External component must be program in the target language; the code must be linked to prototype
- Code is generated using object decomposition from analysis
- Prototype code is optimized using:
  - attributes associated to each object (simple, alternative, terminate)
  - relation between objects.

## **Prototyping Tool**

- **1. Identification Step:** interaction of external component with a system
- 2. Analysis Step:
  - **phase 1**: semi-flow computation
  - **phase 2:** compute all possible process decompositions using semiflows

#### 3. Processes:

Process#1: ProdReady +ProdWait + ProdInit + ProdEnd

Process#2: Cust1\_1 + Cust1\_2 + Cust1\_End

Process#3: Cust2\_1 + Cust2\_2 + Cust2\_End

(tool may ask human for a choice of decomposition; processes have to be named by system designer)

- **phase 3:** all objects and attribute objects are deduced from the model and its process decomposition

### 4. Location and Generation:

- Each process is implemented by a task type (Prod, Cust1, Cust2 are deduced from specification)
- Other tasks manage synchronized Actions also Resources (Resource Manager) and control (Application Manager) – management tasks